# A new Interpolation approach for Sea Temperature and Salinity Enforcing Hydrostatic Equilibrium

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> Introduction

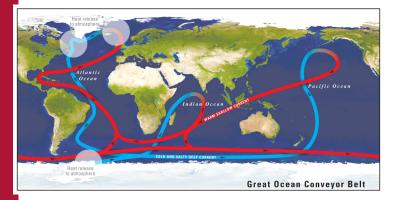
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# Introduction

One of the core topics of phisical oceanography is to study the movement of sea water masses around the globe.





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# What causes the water to move?

Surface current is, intuitively, caused by the wind. What about the bottom layers?

### Thermohaline circulation

In the deep ocean, sea water movements are driven by **temperature** and **salinity** variations which, in turn, cause differences in **density**.

Lighter water masses float over denser ones

The measurement of sea water density is one of the basic tools to study the ocean circulation that affects the earth climate.



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## How do we measure sea water density?

Direct measurement is highly impractical to be performed on the field.

Most of the time it is calculated from in situ **sparse** measurements of Temperature and Salinity.

$$D(t,s) = As + Bs^{3/2} + Cs^{2}$$

$$A = 8.24 \cdot 10^{-1} - 4.08 \cdot 10^{-3}t + 7.64 \cdot 10^{-5}t^{2}$$

$$-8.24 \cdot 10^{-7}t^{3} + 5.38 \cdot 10^{-9}t^{4}$$

$$B = -5.72 \cdot 10^{-3} + 1.022 \cdot 10^{-4}t 1.654 \cdot 10^{-6}t^{2}$$

$$C = 4.8314 \cdot 10^{-4}$$

An instrument called CTD is deployed on water given a sparse set of measurements within an



area



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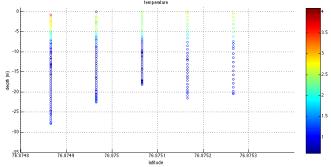
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## How do we interpolate the data samples?

To study the water stratification, the collected sparse samples must be interpolated to a 2D or 3D field



Two common approaches:

- 1. Statistical methods interpolate T and S independently, exploiting spatial properties of the data (No phisical constraints!)
- 2. Model based approaches based on accurate physical simulations (Difficult initialization and boundary conditions!)



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# Our general goal

Interpolate temperature and salinity field in a simple manner without using an accurate phisical model

 But... enforce some basic physical constraint to improve the interpolation

What we suppose?

- All the samples are taken "at the same time"
- Sea water field is stationary (not changing over time)

What must be satisfied?

 Less-dense water must be above denser water (hydrostatic equilibrium)



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# **Problem formulation**

We suppose to have:

- ► A discrete vertical 2D temperature T(i, j) and salinity field S(i, j), defined over a regular grid of M × N points.
- ► A sparse set of N<sub>m</sub> ≪ M × N temperature and salinity measurements taken at certain grid points.

Specifically, let  $T_d(1) \dots T_d(N_m)$  be the temperature measurements taken at grid coordinates  $(i_1^t, j_1^t) \dots (i_{N_m}^t, j_{N_m}^t)$  and  $S_d(1) \dots S_d(N_m)$  be the salinity measurements taken at grid coordinates  $(i_1^s, j_1^s) \dots (i_{N_m}^s, j_{N_m}^s)$ .

► A function D(T<sub>ij</sub>, S<sub>ij</sub>) mapping T(i, j) and S(i, j) to the empirical sea water density at 1 Atm.



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# **Problem formulation**

We pose the temperature and salinity interpolation problem as the following constrained minimization:

 $\begin{aligned} \text{subject to} \quad & D(\mathit{T}_{ij}, \mathit{S}_{ij}) \geq D(\mathit{T}_{i-1\,j}, \mathit{S}_{i-1\,j}), \\ & \forall \ 1 < i \leq M, \ 1 \leq j \leq N \end{aligned}$ 



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# **Problem formulation**

Our goal is to recover T and S given the sparse measurements  $T_d$  and  $S_d$  by simultaneously:

- ► Minimizing the fitting error at the data points. Intuitively, T(i, j) should be almost equal to T<sub>d</sub>(i, j) for each (i, j) = (i<sup>t</sup><sub>k</sub>, j<sup>t</sup><sub>k</sub>). (The same principle is applied to salinity as well)
- Enforcing the hydrostatic equilibrium so that the associated density field gradient is orented downward (ie. the higher grid row, higher the density)
- Minimizing the total squared curvature of T and S



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# Let's see the energy function again...

$$\begin{aligned} \text{subject to} \quad D(T_{ij},S_{ij}) \geq D(T_{i-1\,j},S_{i-1\,j}), \\ \forall \ 1 < i \leq M, \ 1 \leq j \leq N \end{aligned}$$

- Essentially a non linear least squares
- Energy constraints let the optimization difficult to optimize in practice



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#### **Convex relaxation**

We introduce a new scalar field  $D_n$ , and solve the new problem:

$$\begin{array}{ll} \underset{T,S,D_n}{\operatorname{argmin}} & \alpha \sum_{k=1}^{N_m} \left( T(i_k^t, j_k^t) - T_d(k) \right)^2 + \\ & \beta \sum_{k=1}^{N_m} \left( S(i_k^s, j_k^s) - S_d(k) \right)^2 + \\ & \rho_T \sum_i \sum_j \left( \Delta T(i,j) \right)^2 + \\ & \rho_S \sum_i \sum_j \left( \Delta S(i,j) \right)^2 \\ & \rho_D \sum_i \sum_j \left( D(T_{ij}, S_{ij}) - D_n(i,j) \right)^2 \\ & \text{subject to} \\ & D_n(i,j) \geq D_n(i-1,j), \end{array}$$

$$\forall 1 < i \le M, 1 \le j \le N$$

0



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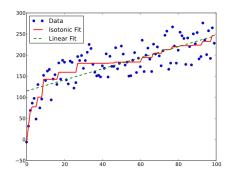
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#### **Isotonic Regression**

Why we did that simplification? There exists an efficient O(n) solution for the problem

 $\begin{array}{ll} \underset{D_n}{\operatorname{argmin}} & \rho_D \sum_i \sum_j \left( D(i,j) - D_n(i,j) \right)^2 \\ \text{subject to} & D_n(i,j) \ge D_n(i-1,j), \\ & \forall \ 1 < i \le M, \ 1 \le j \le N \end{array}$ 

via the so-called Isotonic Regression





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## Numerical solution

To numerically solve the optimization, we iterate between the following two minimizations:

$$\begin{aligned} \underset{T,S}{\operatorname{argmin}} & \alpha \sum_{k=1}^{N_m} \left( T(i_k^t, j_k^t) - T_d(k) \right)^2 + \\ & \beta \sum_{k=1}^{N_m} \left( S(i_k^s, j_k^s) - S_d(k) \right)^2 + \\ & \rho_T \sum_i \sum_j \left( \Delta T(i,j) \right)^2 + \\ & \rho_S \sum_i \sum_j \left( \Delta S(i,j) \right)^2 \\ & \rho_D \sum_i \sum_j \left( D(T_{ij}, S_{ij}) - D_n(i,j) \right)^2 \end{aligned}$$
(1)

$$\begin{array}{ll} \underset{D_n}{\operatorname{argmin}} & \rho_D \sum_i \sum_j \left( D(T_{ij}, S_{ij}) - D_n(i, j) \right)^2 & (2) \\ \text{subject to} & D_n(i, j) \ge D_n(i - 1, j), \\ & \forall \ 1 < i \le M, \ 1 \le j \le N \end{array}$$



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# **Density linearization**

Problem (1) is still non-linear due to the function D. Two ways to overcome the problem:

- Directly optimize (1) via Levenberg-Marquardt (slow)
- Linearize D and take an iterative approach (very fast and effective in this case)

$$\hat{D}(T^{n}, S^{n}) = D(T^{n-1}, S^{n-1}) + + (T^{n} - T^{n-1}) \frac{\delta}{\delta T} D(T^{n-1}, S^{n-1}) + + (S^{n} - S^{n-1}) \frac{\delta}{\delta S} D(T^{n-1}, S^{n-1})$$



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# Solving problem (1)

- Start from an initial interpolation of temperature and salinity
- Iteratively solve:

$$\begin{aligned} \underset{T^{n},S^{n}}{\operatorname{argmin}} & \alpha \sum_{k=1}^{N_{m}} \left( T^{n}(i_{k}^{t},j_{k}^{t}) - T_{d}(k) \right)^{2} + \\ & \beta \sum_{k=1}^{N_{m}} \left( S^{n}(i_{k}^{s},j_{k}^{s}) - S_{d}(k) \right)^{2} + \\ & \rho_{T} \sum_{i} \sum_{j} \left( \Delta T^{n}(i,j) \right)^{2} + \\ & \rho_{S} \sum_{i} \sum_{j} \left( \Delta S^{n}(i,j) \right)^{2} \\ & \rho_{D} \sum_{i} \sum_{j} \left( \hat{D}(T^{n},S^{n}) - D_{n}(i,j) \right)^{2} \end{aligned}$$

Until  $max(|T^n - T^{n-1}|)$  and  $max(|S^n - S^{n-1}|)$  are below a threshold



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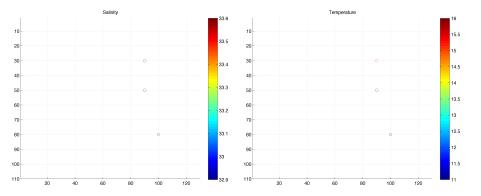
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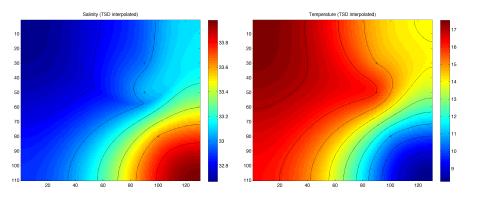
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# Minimizing the whole problem

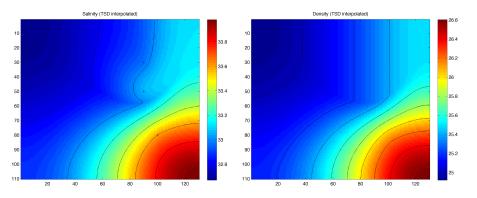
- 1. Compute an initial estimate of T and S (with any interpolation method)
- 2. Compute  $D_n = D(T_{ij}, S_{ij})$
- 3. Solve problem (1) to obtain a new estimate of T and S
- 4. Solve problem (2) via isotonic regression to obtain a new estimate of  $D_n$
- 5. Return to step 3 until convergence



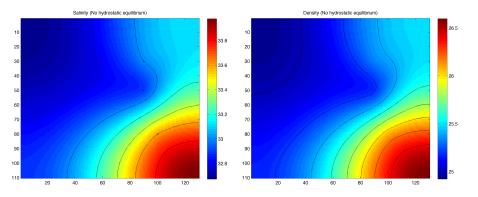
A simple test with just 3 points



Interpolated salinity and temperature fields



Interpolated salinity and density fields



Interpolated result without hydrostatic constraint



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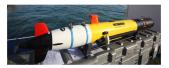
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# Case study: Data from an UAV







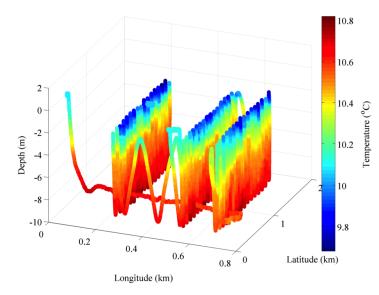
- ▶ REMUS was deployed (Feb 2014) near Isonzo river.
- It acquired data spanning different lat/lon/depth planes





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# Case study: Data from an UAV





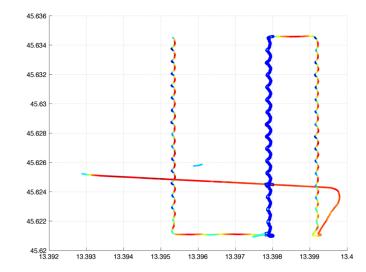
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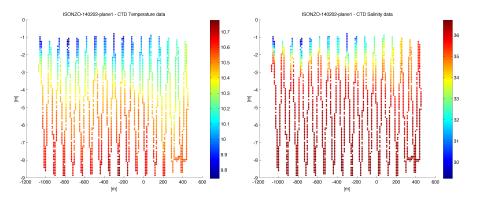
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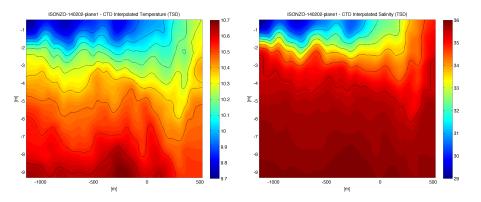
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# Case study: Data from an UAV

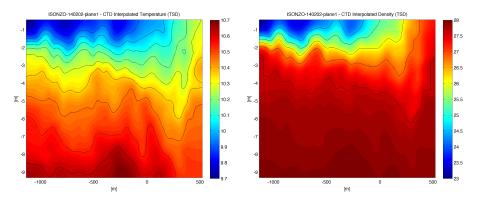




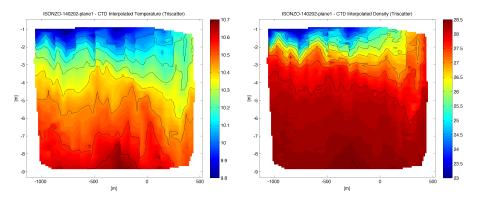
Temperature and salinity



Interpolated Temperature and salinity



Interpolated Temperature and Density



Temperature and Density (Matlab Triscatter interp)



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# Conclusions

- We developed a simple yet powerful interpolation method for sea temperature and salinity
- By enforcing hydrostatic equilibrium we both ensure some physical properties of the field and improve the interpolation even with few data
- Preliminary synthetic tests demonstrate the potentials of such approach

#### For the future?

- ▶ Give an estimate of the interpolation error over the field
- 3D interpolation
- Consider the temporal extent of the data to introduce additional constraints on the velocity fields



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Thank you for your attention http://dsi.unive.it/~bergamasco filippo.bergamasco@unive.it